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Rodic, M.; Jezernik, K.;

Industrial Electronics, 1999. ISIE '99. Proceedings of the IEEE International Symposium on , Volume: 2 , 12-16 July 1999

Pages:641 - 646 vol.2

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## 2 Control of the Furuta pendulum based on a linear differential flatnes approach

Aguilar-Ibanez, C.; Sira-Ramirez, H.;

American Control Conference, 2002. Proceedings of the 2002, Volume: 3, 8-May 2002

Pages:1954 - 1959 vol.3

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## 3 Multivariable saturating control and antiwindup control for the phan 500 body motion: a comparison

Folcher, J.-P.;

OCEANS 2003. Proceedings, Volume: 2, 22-26 Sept. 2003

Pages:711 Vol.2

[Abstract] [PDF Full-Text (195 KB)]

## 4 Output feedback control for output tracking of nonlinear uncertain systems

Gibbens, P.W.; Fu, M.;

Decision and Control, 1991., Proceedings of the 30th IEEE Conference on , 11 Dec. 1991

Pages:2509 - 2514 vol.3

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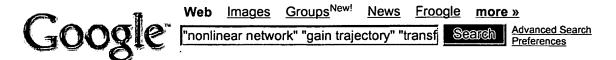


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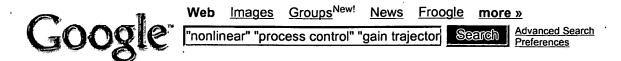
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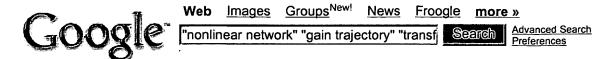
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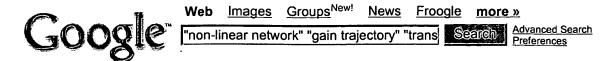
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